

Advanced Econometrics

Chapter 2: The Classical Multiple Linear Regression Model

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Linear Regression Model

Reading: Chapter 2 of Greene

- Notation:

y_i : dependent variable, regressand

x_{i1}, \dots, x_{iK} : independent variables, explanatory variables, control variables, regressors

i : index.

- We want to explain y_i using x_{i1}, \dots, x_{iK} . The multiple linear regression model takes the form

$$\begin{aligned}y_i &= \beta_1 x_{i1} + \dots + \beta_K x_{iK} + \varepsilon_i \quad (i = 1, \dots, n) \\ &= x_i' \beta + \varepsilon_i\end{aligned}$$

where

$$x_i = \begin{pmatrix} x_{i1} \\ \vdots \\ x_{iK} \end{pmatrix}, \quad \beta = \begin{pmatrix} \beta_1 \\ \vdots \\ \beta_K \end{pmatrix} \quad \text{and } x_{i1} = 1 \text{ for all } i.$$

Linear Regression Model

- Equivalently, in matrix notation,

$$\begin{aligned}y &= \mathbf{x}_1\beta_1 + \cdots + \mathbf{x}_K\beta_K + \varepsilon \\ &= \mathbf{X}\beta + \varepsilon\end{aligned}$$

where

$$y = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}, \quad \mathbf{x}_l = \begin{pmatrix} x_{1l} \\ \vdots \\ x_{nl} \end{pmatrix} \quad (l = 1, \dots, K)$$

Linear Regression Model

$$\begin{aligned} X &= (\mathbf{x}_1, \dots, \mathbf{x}_K) \\ &= \begin{pmatrix} x'_1 \\ \vdots \\ x'_n \end{pmatrix} \end{aligned}$$

and

$$\boldsymbol{\varepsilon} = \begin{pmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{pmatrix}.$$

Here ε_j is an error term.

Linear Regression Model

- *Loglinear model:*

$$\ln y = \beta_1 + \beta_2 \ln x_2 + \cdots + \beta_K \ln x_K + \varepsilon$$

$$\frac{\partial \ln y}{\partial \ln x_k} = \frac{\partial y / y}{\partial x_k / x_k} = \beta_k \text{ (constant elasticity)}$$

- *Semilog model:*

$$\ln y_t = X_t' \beta + \delta t + \varepsilon_t$$

Per period growth rate of y_t not explained by X_t is

$$\frac{d \ln y}{dt} = \delta$$

- *Polynomial equation*

$$y = \beta_1 + \beta_2 x + \beta_3 x^2 + \cdots + \beta_p x^{p-1} + \varepsilon.$$

- *Interaction model*

$$y = \beta_1 + \beta_2 x + \beta_3 z + \beta_p xz + \varepsilon.$$

Example

Interaction model

$$D = \beta_1 + \beta_2 S + \beta_3 W + \beta_4 SW + \varepsilon$$

D : breaking distance

W : road wetness

S : speed

$$\frac{\partial D}{\partial S} = \beta_2 + \beta_4 W$$

If $\beta_4 > 0$, the marginal effect of higher speed on breaking distance is increased when the road is wetter.

Example

Earnings and education

$$\text{earnings}_i = \beta_1 + \beta_2 \text{education}_i + \varepsilon_i$$

earnings_i : i - th individual's hourly earning

education_i : i - th individual's number of years in school

Any problems in the model?

Omitted variables such as job experience, job experience², gender, marital status, etc.

$$\begin{aligned} \text{earnings}_i = & \beta_1 + \beta_2 \text{education}_i + \beta_3 \text{job experience}_i + \beta_4 \text{job experience}_i^2 \\ & + \beta_5 \text{gender}_i + \beta_6 \text{marital status}_i + \varepsilon_i \end{aligned}$$

Example

Earnings and education (Continued)

For gender and marital status, use dummy variables. That is,

$$\text{gender}_i \begin{cases} = 1 & \text{if male} \\ = 0 & \text{if female} \end{cases}$$

$$\text{marital status}_i \begin{cases} = 1 & \text{if married} \\ = 0 & \text{if single} \end{cases}$$

See, for example, Ashenfelter and Krueger, *American Economic Review*, 1994, 73–85.

Example

Class attendance and test scores

$$\text{score}_i = \beta_1 + \beta_2 (\text{fraction of lectures attended})_i + \beta_3 (\text{fraction of problem sets completed})_i + \varepsilon_i$$

See Romer, Journal of Economic Perspectives, 1993.

Example

Threshold effects and categorical variables

$$income = \beta_1 + \beta_2 age + \delta_B B + \delta_M M + \delta_P P + \varepsilon$$

$$B \begin{cases} = 1, & \text{Bachelor's degree only} \\ = 0, & \text{otherwise} \end{cases}$$

$$M \begin{cases} = 1, & \text{Master's and Bachelor's degrees} \\ = 0, & \text{otherwise} \end{cases}$$

$$P \begin{cases} = 1, & \text{Ph.D., Master's and Bachelor's degrees} \\ = 0, & \text{otherwise} \end{cases}$$

Example

Threshold effects and categorical variables

High school

$$E [Income|age, HS] = \beta_1 + \beta_2 age$$

Bachelor's

$$E [Income|age, B] = \beta_1 + \beta_2 age + \delta_B$$

Master's

$$E [Income|age, M] = \beta_1 + \beta_2 age + \delta_B + \delta_M$$

Ph.D.

$$E [Income|age, P] = \beta_1 + \beta_2 age + \delta_B + \delta_M + \delta_P$$

Example

Seasonal effects

Suppose y_t is a quarterly data

$$y_t = \beta_1 + \beta' X_t + \delta_1 D_{1t} + \delta_2 D_{2t} + \delta_3 D_{3t} + \varepsilon_t.$$

Here X_t does not contain 1.

$$D_{1t} \begin{cases} = 1, & \text{if spring} \\ = 0, & \text{otherwise} \end{cases}$$

$$D_{2t} \begin{cases} = 1, & \text{if summer} \\ = 0, & \text{otherwise} \end{cases}$$

$$D_{3t} \begin{cases} = 1, & \text{if fall} \\ = 0, & \text{otherwise} \end{cases}$$

Definition

For two continuous random variables, X and Y , we say that the conditional probability density function (pdf) of Y given $X = x$ is

$$f_{Y|X}(y|x) = \frac{f(x, y)}{f_X(x)}$$

where $f(x, y)$ is the joint pdf of X and Y and $f_X(x)$ is the marginal pdf of X .

Remark

- (i) $f_{Y|X}(y|x)$ is a function of x and possibly a different pdf for each x .
- (ii) When we wish to describe the entire family of pdf, we use the phrase “the pdf of $Y | X$ ”.
- (iii) If X and Y are independent,

$$f_{Y|X}(y|x) = f_Y(y)$$

Conditional expectation

Definition

A conditional mean is the mean of the conditional distribution and is defined by

$$E(Y|X = x) = \begin{cases} \int_y y f_{Y|X}(y|x) dy & \text{if } y \text{ is continuous} \\ \sum_y y f_{Y|X}(y|x) & \text{if } y \text{ is discrete} \end{cases}$$

Remark

(i) Note that

$$E[Y|X = x] = E[Y]$$

if X and Y are independent.

(ii) $E(Y | X)$ is a random variable whose value depends on X .

- The Law of Iterated Expectations

$$E(X) = E[E(X|Y)].$$

This holds because

$$\begin{aligned} E(X) &= \int \int xf(x, y) dx dy \\ &= \int \left[\int xf(x | y) dx \right] f_Y(y) dy \\ &= \int [E(X | y)] f_Y(y) dy \\ &= E(X | Y). \end{aligned}$$



$$E[g(Y)h(X)|X] = h(X)E[g(Y)|X]$$

Trivially, $E[g(Y)h(X)|X = x] = h(x)E[g(Y)|X = x]$. But this holds for any $x \in R$. Thus, the stated result holds. See, e.g., Ash (1972) for a formal proof.

Assumptions

1. Full rank

- X is an $n \times K$ matrix with rank K .
 - The columns of X are linearly independent.
 - Obviously, we should have $n \geq K$.
 - If this assumption is violated, X contains redundant information.
 - We allow stochastic regressors.

Assumptions

1. Full rank (continued)

- What if this assumption is violated?

Suppose that

$$y = \beta_1 + \beta_2 X_1 + \beta_3 X_2 + \varepsilon$$

and

$$X_1 = \alpha X_2.$$

Then, the ordinary least squares estimator does not exist. When X is of deficient rank, we say that there is a multicollinearity problem.

Assumptions

2. Zero conditional mean of the disturbance



$$E(\varepsilon|X) = \begin{bmatrix} E(\varepsilon_1|X) \\ \vdots \\ E(\varepsilon_n|X) \end{bmatrix} = 0.$$

Whatever the value of X is, the mean of ε is zero. This assumption implies

$$E(\varepsilon_i) = 0$$

(this follows from the law of iterated expectation) and

$$\text{Cov}(\varepsilon_i, x_j) = E[\varepsilon_i (x_j - E(x_j)')] = 0 \text{ for all } i.$$

Assumptions

2. Zero conditional mean of the disturbance

- In fact, ε_i is uncorrelated with any function of x_i .

$$\begin{aligned} \text{Cov}(\varepsilon_i, f(x_i)) &= E \left[\varepsilon_i \{f(x_i) - Ef(x_i)\}' \right] \\ &= EE \left[\varepsilon_i \{f(x_i) - Ef(x_i)\}' \mid x_i \right] \\ &= E \left[\{f(x_i) - Ef(x_i)\}' E(\varepsilon_i \mid x_i) \right] \\ &= 0. \end{aligned}$$

Assumptions

3. Spherical disturbances

- $$\begin{cases} \text{Var}(\varepsilon_i|X) = \sigma^2 \text{ for all } i = 1, 2, \dots, n \\ \text{Cov}(\varepsilon_i, \varepsilon_j|X) = 0 \text{ for all } i \neq j. \end{cases}$$

These imply

$$\begin{aligned} E(\varepsilon\varepsilon'|X) &= \begin{bmatrix} E(\varepsilon_1^2|X) & E(\varepsilon_1\varepsilon_2|X) & \cdots & E(\varepsilon_1\varepsilon_n|X) \\ & \ddots & & \\ & & & \\ & & & E(\varepsilon_n^2|X) \end{bmatrix} \\ &= \sigma^2 I. \end{aligned}$$

The assumption of common variance for ε_i is called homoskedasticity.

Assumptions

- Alternatively, we may assume
 - 1 X is an $n \times K$ nonstochastic matrix with rank K .
 - 2 $\varepsilon_j \sim iid(0, \sigma^2)$.
- These assumptions are more restrictive.

Partial effects, elasticity and average partial effect

- The partial derivative of $E(y | X)$ with respect to x_j is called the partial effect of x_j on $E(y | X)$.
- The elasticity of $E(y | X)$ with respect to x_j , holding other variables fixed, is

$$\frac{\partial E(y | X)}{\partial x_j} \cdot \frac{x_j}{E(y | X)}$$

Example

Let

$$E(y | X) = \beta_0 + \beta_1 x_1 + \beta_2 x_2.$$

$$\frac{\partial E(y|X)}{\partial x_1} = \beta_1 \text{ and } \frac{\partial E(y|X)}{\partial x_2} = \beta_2.$$

Partial effects, elasticity and average partial effect

- Suppose that $E(y | X, q) = \mu(X, q)$, where q is not observed. Let $\theta_j(X, q) = \frac{\partial \mu(X, q)}{\partial x_j}$. The average partial effect (APE) of x_j is

$$E_q \theta_j(X, q).$$